

## **Using FOCAS Libraries in the TMA55OP Flexible Manufacturing Cell** **Csokmai Lehel Szabolcs<sup>1</sup>**

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**Keywords:** FOCAS, LAN, network.

**Abstract:** FOCAS libraries are used for exchanging data and information between a personal computer and the CNC/PMC through the HSSB or Ethernet. The FOCAS libraries are used with the Visual Studio Integrated Development Environment. The software was written in the C# programming language using the .NET Framework 2.0 .

### **1. Introduction**

FOCAS libraries are used for exchanging data and information between a personal computer and the CNC/PMC through the HSSB or Ethernet. The FOCAS libraries are used with the Visual Studio Integrated Development Environment. The software was written in the C# programming language using the .NET Framework 2.0 .

The main features of the FOCAS libraries are:

- read/write data related to axes/spindle, absolute positions, machine positions, remaining distance to go
- operations related to CNC program, upload/download, search, delete
- read/write CNC file data, tool offset data, workpiece reference point offset data, parameters
- read/write tool life data
- read history data, operation history and alarm history
- read/write data related to PMC

### **2. Presentation**

Every application built with the help of FOCAS libraries have to establish the communication with the CNC. It is necessary to get the library handle number before calling any function. The library handle number can be obtained with the use of `cnc_allclibhdl` function. The following code is used to get the library handle number from the CNC:

```
Focas1.focas_ret ret = (Focas1.focas_ret)Focas1.cnc_allclibhdl(out cncHandle);
```

The `cncHandle` variable contains the library handle number. The type of the `cncHandle` variable is `ushort`. The `ret` variable contains the status message received from the CNC. If `ret` is `EW_OK` then the function is executed successfully, otherwise the following major error codes are returned:

- `EW_HSSB`, communication error
- `EW_HANDLE`, acquiring of handle is failed
- `EW_BUSY`, initialization between MMC function and CNC/PMC is in progress

Once the library handle number is acquired, it must be held until the termination of the application.

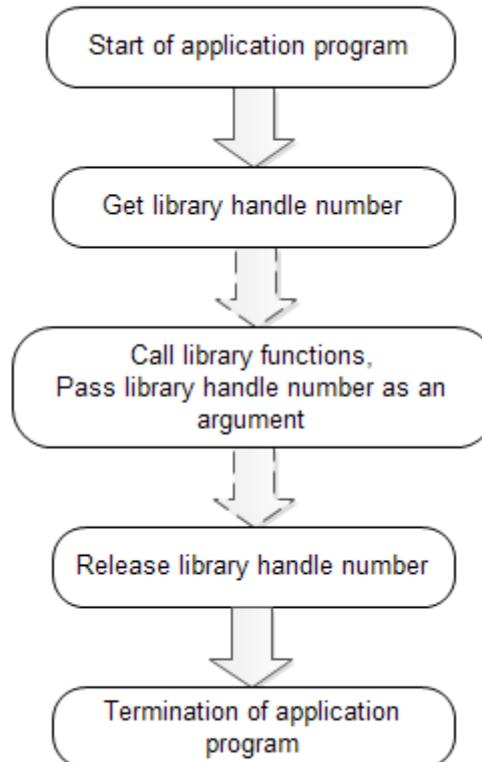


Figure 1. Processing sequence

When the application terminates, the library handle must be released by using the `cnc_freelibhndl` function.

```
if (cncHandle != 0) Focas1.cnc_freelibhndl(cncHandle);
```

Using the `cnc_sysinfo`, we can get various system informations such as:

- Maximum controlled axes
- Kind of CN
- Kind of M/T/TT
- Series number
- Version number
- Current controlled axes
- 

```
Focas1.ODBSYS sysinfo_01 = new Focas1.ODBSYS();  
Focas1.cnc_sysinfo(cncHandle, sysinfo_01);  
string str_cnc_type = new string(sysinfo_01.cnc_type);
```

The `cnc_rdposition` function reads the positions from first axis to the specified axis number. The absolute, machine, relative and distance positions can be showed with the help of this function.

```
Focas1.ODBPOS pos = new Focas1.ODBPOS();  
Focas1.cnc_rdposition(cncHandle, 0, ref 32, pos);
```

The `pos` variable contains the requested positions and can be used to show the following data:

- data, position data (`pos.p1.abs.data`)
- dec, decimal place (`pos.p1.abs.dec`)
- unit (`pos.p1.abs.unit`)
- name (`pos.p1.abs.name`)

The `pmc_rdpmcrng` function reads the PMC data of the specified PMC address/range. This function is used to exchange data between the application on MMC function and LADDER software on PMC.

```
Focas1.IODBPMC0 pmcData = new Focas1.IODBPMC0();  
Focas1.focas_ret ret = (Focas1.focas_ret)Focas1.pmc_rdpmcrng(cncHandle, 5, 0, 16, 19,  
12, pmcData);
```

The above functions will read byte data from the addresses R0016 - R0019.

- `adr_type` is relay (5)
- `data_type` is byte (0)
- `s_number`, start PMC address number
- `e_number`, end PMC address number
- `length`, 8 + addresses

The results are posted with the help of the following lines:

```
string str_0_bits = Convert.ToString(pmcData.cdata[0], 2);
```

This line converts the R0016 value binary. The maximum number which can be returned is 255 (11111111).

### 3. Conclusions

With the help of the FOCAS libraries we can build custom applications for the TMA55OP flexible manufacturing cell. Adding a simple socket client and server modules to this application will make the application communicate over a simple ethernet (TCP/IP) network.

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